

# MHD Wave Analysis

## in Cartesian and Cylindrical Coordinates

Hanbyul Jang, Dongsu Ryu

*Department of Physics, School of Natural Sciences, UNIST, Korea*



*Astrophysics Laboratory*  
*hanbyul@sirius.unist.ac.kr*

# 1. Cartesian Coordinate

## MHD equations

Primitive forms

density  $\frac{D\rho}{Dt} + \nabla \cdot (\rho \mathbf{v}) = 0$

velocity  $\rho \frac{D\mathbf{v}}{Dt} = -\nabla p - \nabla \times (\nabla \times \mathbf{B}) \times \mathbf{B}$

magnetic induction  $\nabla \times (\mathbf{v} \times \mathbf{B}) = 0$

Gauss law  $\nabla \cdot \mathbf{B} = 0$

adiabatic index

pressure  $\frac{Dp}{Dt} + \nabla \cdot (p \mathbf{v}) = 0$

# 1. Cartesian Coordinate

## MHD equations

density  $\rho = \rho_0 + \rho_1(x)$

velocity  $\mathbf{v} = v_1(x)\mathbf{e}_1$

magnetic induction  $\mathbf{B} = B_1(x)\mathbf{e}_1 + B_2(x)\mathbf{e}_2 + B_3(x)\mathbf{e}_3$

Gauss law  $\nabla \cdot \mathbf{B} = 0$

pressure  $p = p_0 + p_1(x)$

1D  $\nabla \rightarrow \frac{d}{dx}$

1-dimension  one variation only (here, x)

# Linearization

initial condition

$$\frac{\partial p}{\partial t} + \frac{\partial}{\partial x} (p v_x) = 0$$

$$p \frac{\partial v_x}{\partial t} + p v_x \frac{\partial v_x}{\partial x} + \frac{\partial p}{\partial x} + B v_x - \frac{\partial B}{\partial x} v_x + B \frac{\partial v_x}{\partial x} = 0$$

$$p \frac{\partial v_x}{\partial t} + p v_x \frac{\partial v_x}{\partial x} - B \frac{\partial v_x}{\partial x} = 0$$

$$p \frac{\partial v_x}{\partial t} + p v_x \frac{\partial v_x}{\partial x} - B \frac{\partial v_x}{\partial x} = 0$$

$$\frac{\partial B}{\partial t} = 0 \quad \frac{\partial B}{\partial x} = 0 \quad \Rightarrow \quad B_x = \text{constant}$$

$$\frac{\partial B}{\partial t} + \frac{\partial}{\partial x} (B v_x - B v_x) = 0$$

$$\frac{\partial B}{\partial t} + \frac{\partial}{\partial x} (B v_x - B v_x) = 0$$

$$\frac{\partial p}{\partial t} + v_x \frac{\partial p}{\partial x} + p \frac{\partial v_x}{\partial x} = 0$$

$$\vec{v} = \vec{v}_0 + \vec{v}'(t, x)$$

$$p = p_0 + \delta p$$

$$v_x = v_{x0} + \delta v_x$$

$$v_y = v_{y0} + \delta v_y$$

$$v_z = v_{z0} + \delta v_z$$

$$B_x = B_{x0}$$

$$B_y = B_{y0} + \delta B_y$$

$$B_z = B_{z0} + \delta B_z$$

$$p = p_0 + \delta p$$

# Linearization

$$-\frac{\partial \dot{p}}{\partial t} + \frac{\partial}{\partial z} (p v) = 0 \quad \dot{p} \ll 1 \quad \rightarrow$$

more than second order terms dropped out

$$p \frac{\partial v}{\partial t} + \frac{\partial}{\partial z} (p v^2 + B v) = 0$$

$$p \frac{\partial v}{\partial t} + \frac{\partial}{\partial z} (p v^2 - B v) = 0$$

$$p \frac{\partial v}{\partial t} + \frac{\partial}{\partial z} (p v^2 - B v) = 0$$

$$-\frac{\partial \dot{B}}{\partial t} + \frac{\partial}{\partial z} (B v) = 0$$

$$-\frac{\partial \dot{B}}{\partial t} + \frac{\partial}{\partial z} (B v) = 0$$

$$-\frac{\partial \dot{p}}{\partial t} + \frac{\partial}{\partial z} (p v) = 0$$

$$\dot{p} \propto e^{i(\omega t - k z)}$$

# Linearization

$$v \delta p - k (p_{11} \delta v_1 + v_{11} \delta p) = 0$$

$$v p_{11} \delta v_1 - k (p_{11} v_{11} \delta v_1 + \delta p + B_{11} \delta B_{11} + B_{11} \delta B_{11}) = 0$$

$$v p_{11} \delta v_1 - k (p_{11} v_{11} \delta v_1 - B_{11} \delta B_{11}) = 0$$

$$v p_{11} \delta v_1 - k (p_{11} v_{11} \delta v_1 - B_{11} \delta B_{11}) = 0$$

$$v \delta B_{11} - k (B_{11} \delta v_1 - B_{11} \delta v_1 + v_{11} \delta B_{11}) = 0$$

$$v \delta B_{11} - k (B_{11} \delta v_1 - B_{11} \delta v_1 + v_{11} \delta B_{11}) = 0$$

$$v \delta p - k (p_{11} \delta v_1 + v_{11} \delta p) = 0$$

Eigen mode

$$v = \frac{v}{k} = v_{11} + \lambda$$

# Eigen modes

$$\begin{pmatrix}
 \rho & 0 & 0 & 0 & 0 & 0 \\
 0 & \rho & 0 & 0 & 0 & 0 \\
 0 & 0 & \rho & 0 & 0 & 0 \\
 0 & 0 & 0 & \rho & 0 & 0 \\
 0 & 0 & 0 & 0 & \rho & 0 \\
 0 & 0 & 0 & 0 & 0 & \rho
 \end{pmatrix}
 \begin{pmatrix}
 \delta \rho \\
 \delta v_x \\
 \delta v_y \\
 \delta v_z \\
 \delta p \\
 \delta \rho
 \end{pmatrix}
 =
 \begin{pmatrix}
 -\rho \delta v_x \\
 -\rho \delta v_y \\
 -\rho \delta v_z \\
 -\rho \delta v_x \\
 -\rho \delta v_y \\
 -\rho \delta v_z
 \end{pmatrix}$$

$\det \begin{pmatrix} \rho & 0 & 0 & 0 & 0 & 0 \\ 0 & \rho & 0 & 0 & 0 & 0 \\ 0 & 0 & \rho & 0 & 0 & 0 \\ 0 & 0 & 0 & \rho & 0 & 0 \\ 0 & 0 & 0 & 0 & \rho & 0 \\ 0 & 0 & 0 & 0 & 0 & \rho \end{pmatrix} = \rho^6$

entropy    Alfven    compressible (fast, slow)

1. entropy  $\begin{pmatrix} \rho \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$

2. Alfven  $\begin{pmatrix} 0 \\ \rho \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$

3. compressible  $\begin{pmatrix} 0 \\ 0 \\ 0 \\ \rho \\ 0 \\ 0 \end{pmatrix}$

# Wave analysis

## 1. entropy

$$\begin{aligned} \mathbf{v} &= \mathbf{v}_0 + \mathbf{v}_1 + \mathbf{v}_2 + \dots \\ \mathbf{v}_0 &= \mathbf{v}_0 \\ \mathbf{v}_1 &= -\frac{1}{c^2} \nabla \phi_1 \\ \mathbf{v}_2 &= \frac{1}{c^2} \nabla \phi_2 \\ \mathbf{v}_3 &= -\frac{1}{c^2} \nabla \phi_3 \\ \mathbf{v}_4 &= \frac{1}{c^2} \nabla \phi_4 \\ \mathbf{v}_5 &= -\frac{1}{c^2} \nabla \phi_5 \\ \mathbf{v}_6 &= \frac{1}{c^2} \nabla \phi_6 \\ \mathbf{v}_7 &= -\frac{1}{c^2} \nabla \phi_7 \\ \mathbf{v}_8 &= \frac{1}{c^2} \nabla \phi_8 \\ \mathbf{v}_9 &= -\frac{1}{c^2} \nabla \phi_9 \\ \mathbf{v}_{10} &= \frac{1}{c^2} \nabla \phi_{10} \end{aligned}$$

## 2. Alfven

$$\begin{aligned} \mathbf{v} &= \mathbf{v}_0 + \mathbf{v}_1 + \mathbf{v}_2 + \dots \\ \mathbf{v}_0 &= \mathbf{v}_0 \\ \mathbf{v}_1 &= -\frac{1}{c^2} \nabla \phi_1 \\ \mathbf{v}_2 &= \frac{1}{c^2} \nabla \phi_2 \\ \mathbf{v}_3 &= -\frac{1}{c^2} \nabla \phi_3 \\ \mathbf{v}_4 &= \frac{1}{c^2} \nabla \phi_4 \\ \mathbf{v}_5 &= -\frac{1}{c^2} \nabla \phi_5 \\ \mathbf{v}_6 &= \frac{1}{c^2} \nabla \phi_6 \\ \mathbf{v}_7 &= -\frac{1}{c^2} \nabla \phi_7 \\ \mathbf{v}_8 &= \frac{1}{c^2} \nabla \phi_8 \\ \mathbf{v}_9 &= -\frac{1}{c^2} \nabla \phi_9 \\ \mathbf{v}_{10} &= \frac{1}{c^2} \nabla \phi_{10} \end{aligned}$$

## 3. compressible

$$\begin{aligned} \mathbf{v} &= \mathbf{v}_0 + \mathbf{v}_1 + \mathbf{v}_2 + \dots \\ \mathbf{v}_0 &= \mathbf{v}_0 \\ \mathbf{v}_1 &= -\frac{1}{c^2} \nabla \phi_1 \\ \mathbf{v}_2 &= \frac{1}{c^2} \nabla \phi_2 \\ \mathbf{v}_3 &= -\frac{1}{c^2} \nabla \phi_3 \\ \mathbf{v}_4 &= \frac{1}{c^2} \nabla \phi_4 \\ \mathbf{v}_5 &= -\frac{1}{c^2} \nabla \phi_5 \\ \mathbf{v}_6 &= \frac{1}{c^2} \nabla \phi_6 \\ \mathbf{v}_7 &= -\frac{1}{c^2} \nabla \phi_7 \\ \mathbf{v}_8 &= \frac{1}{c^2} \nabla \phi_8 \\ \mathbf{v}_9 &= -\frac{1}{c^2} \nabla \phi_9 \\ \mathbf{v}_{10} &= \frac{1}{c^2} \nabla \phi_{10} \end{aligned}$$



# Alfven wave test

2. +Alfven  $\lambda = b_{x0}$



$$\propto \left( \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right)$$

## Initial condition for plus Alfven wave

### Backgrounds

$$\begin{aligned}\rho_0 &= 1 \\ v_{x0} &= 0 \\ v_{y0} &= 0 \\ v_{z0} &= 0 \\ B_{x0} &= 1 \\ B_{y0} &= 0.5 \\ B_{z0} &= 0 \\ p_0 &= 1/\gamma\end{aligned}$$

### Perturbations

$$\begin{aligned}\delta\rho &= 0 \\ \delta v_x &= 0 \\ \delta v_y &= 0 \\ \delta v_z &= 10^{-4} \cos(kx) \\ \delta B_x &= 0 \\ \delta B_y &= 0 \\ \delta B_z &= -\sqrt{\rho_0} \delta v_z \\ \delta p &= 0\end{aligned}$$

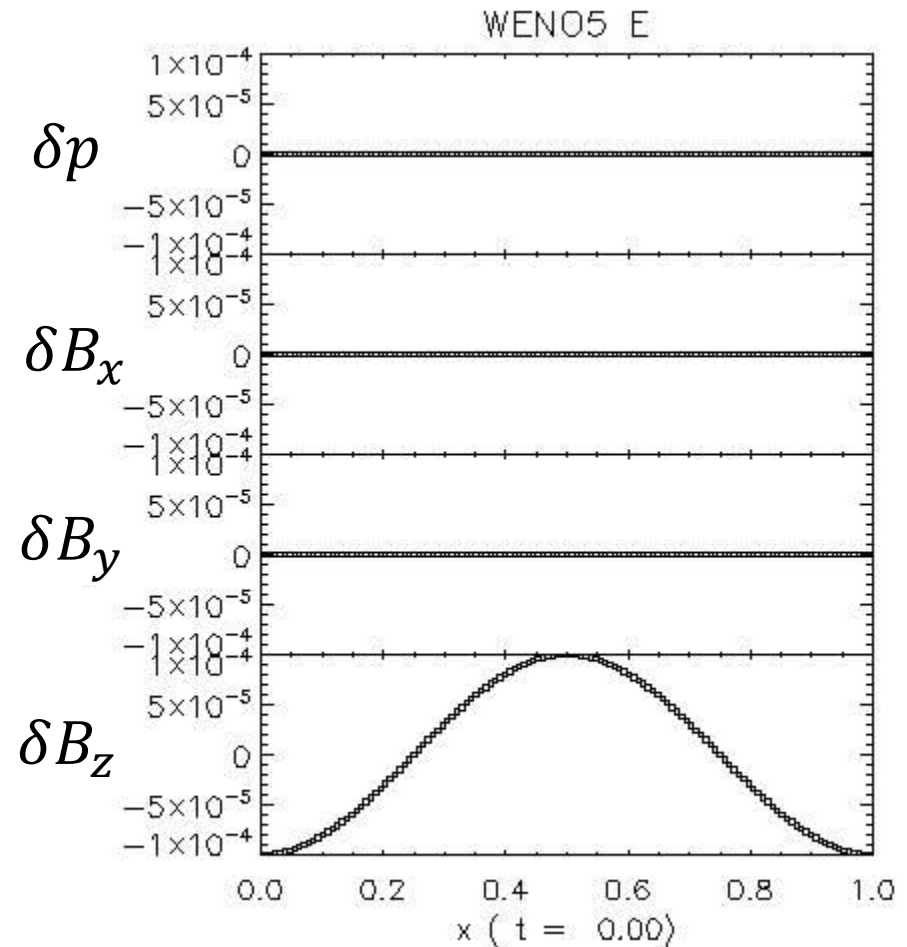
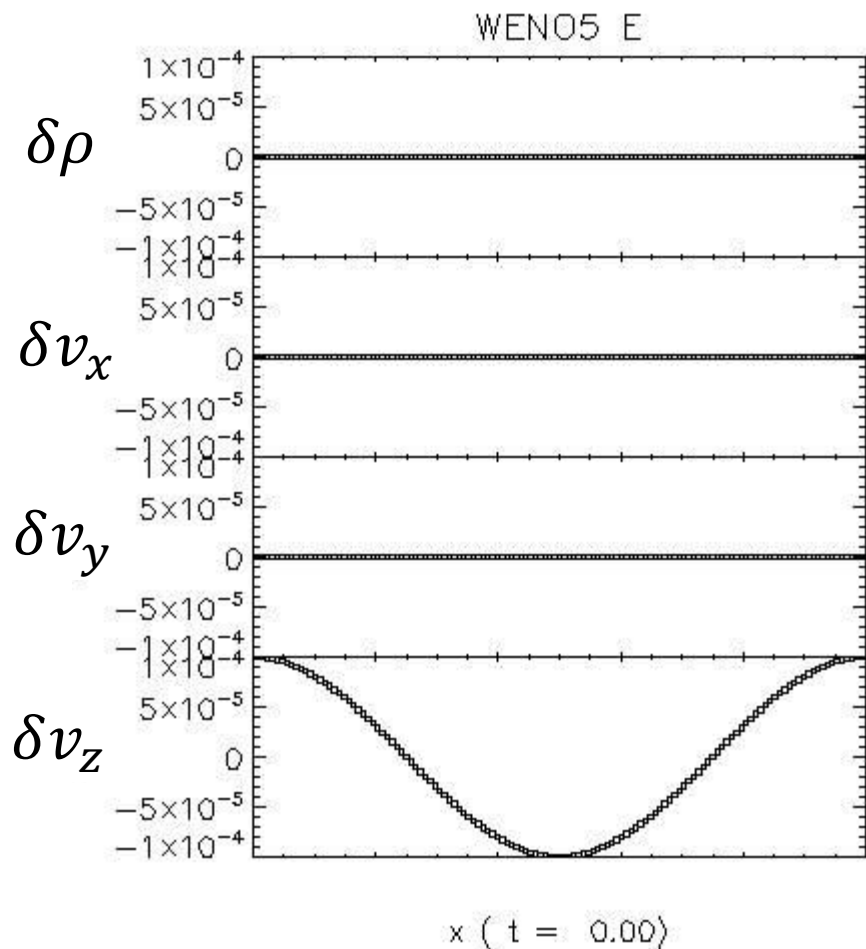
### Total

$$\begin{aligned}\rho &= \rho_0 + \delta\rho \\ v_x &= v_{x0} + \delta v_x \\ v_y &= v_{y0} + \delta v_y \\ v_z &= v_{z0} + \delta v_z \\ B_x &= B_{x0} \\ B_y &= B_{y0} + \delta B_y \\ B_z &= B_{z0} + \delta B_z \\ p &= p_0 + \delta p\end{aligned}$$

# Alfven wave test 1. Code verification

## Test Code

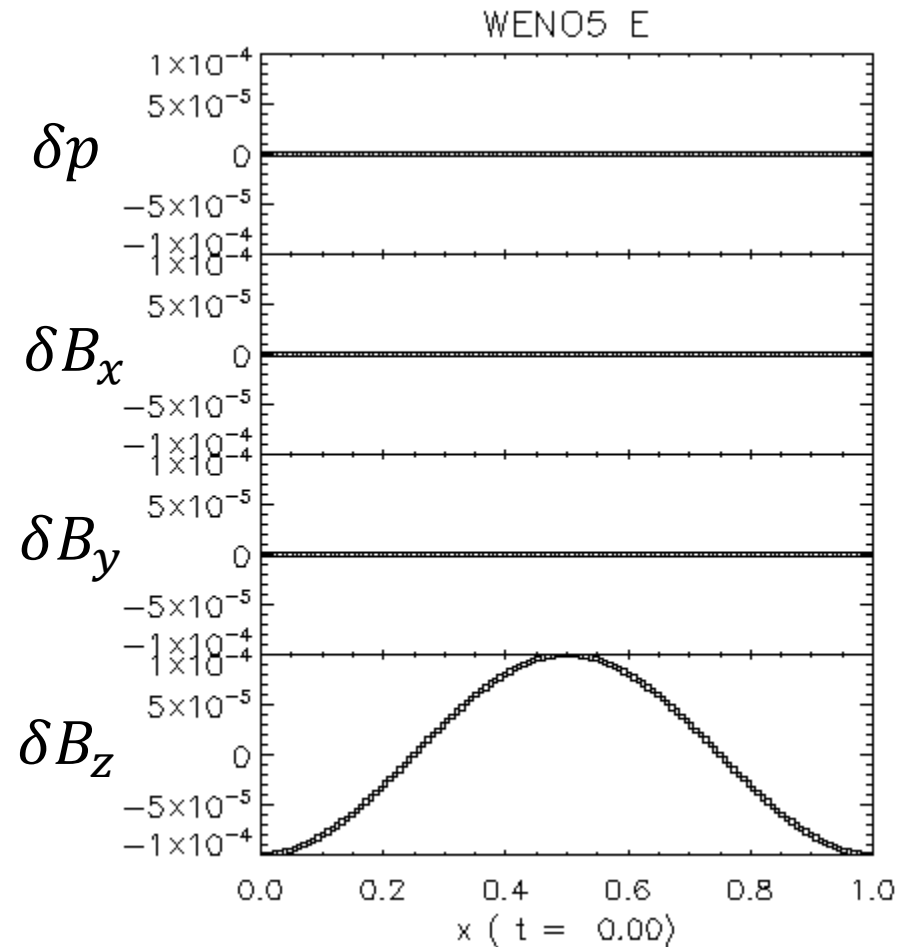
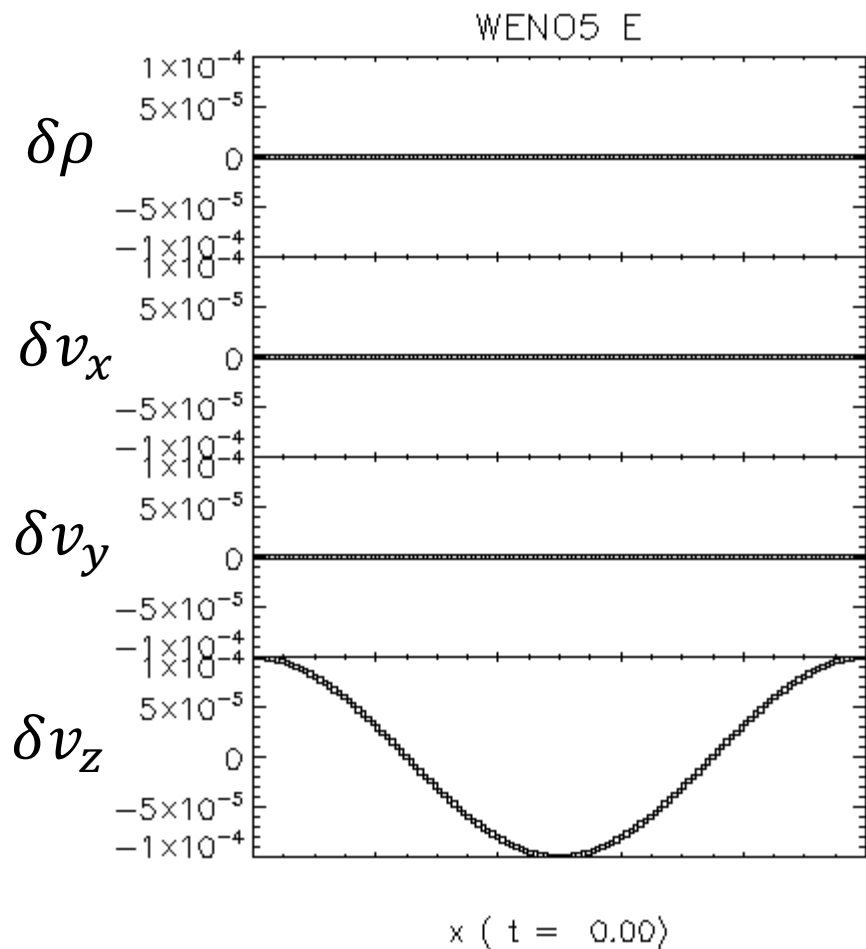
- MHD 5<sup>th</sup> order WENO
- periodic boundary condition
- resolution = 128 , tend = 1.0



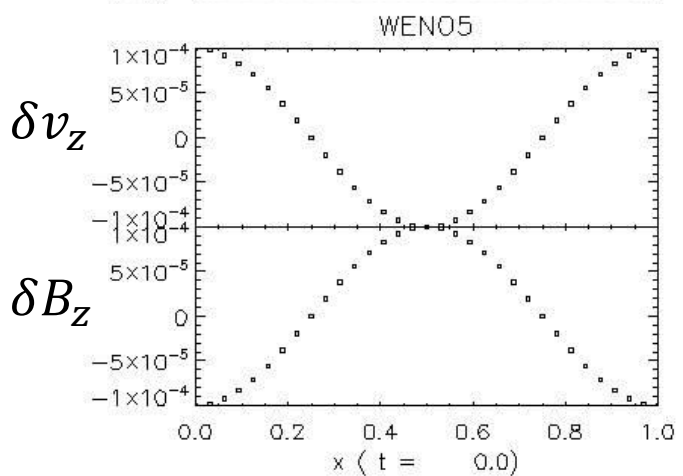
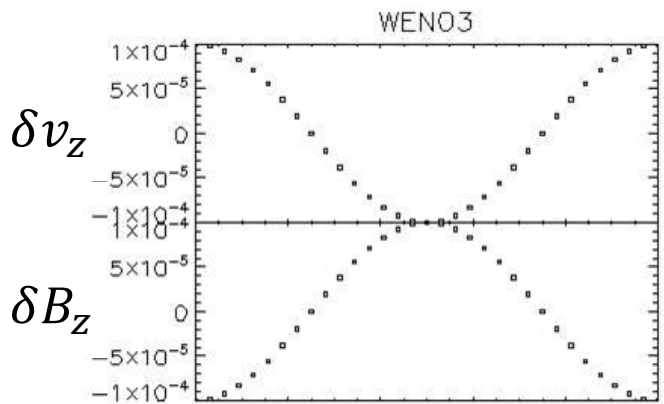
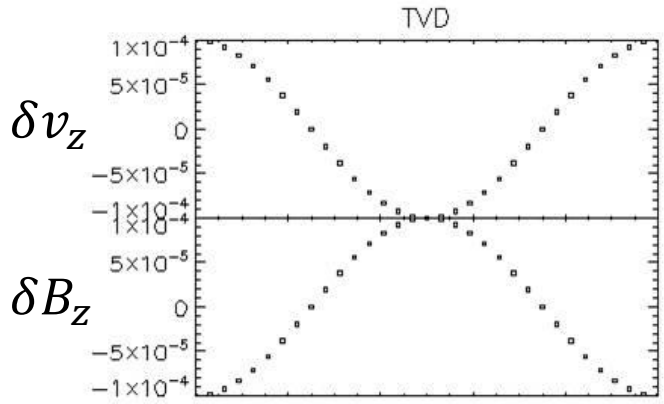
# Alfven wave test 1. Code verification

## Test Code

- MHD 5<sup>th</sup> order WENO
- periodic boundary condition
- resolution = 128 , tend = 1.0



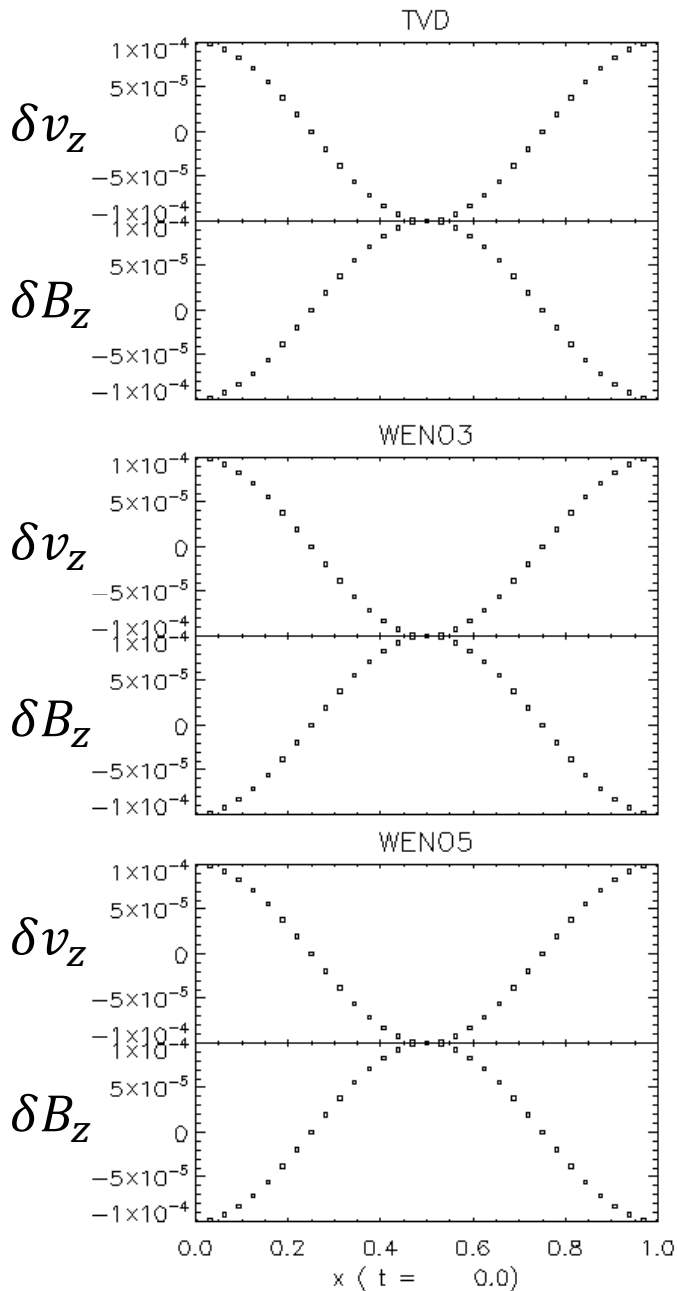
# Alfven wave test $\rightarrow$ 2. Order Check



## Test Code

- 2<sup>nd</sup> order TVD
- 3<sup>rd</sup> order WENO3
- 5<sup>th</sup> order WENO5
- resolution = 32 tend = 100

# Alfven wave test $\rightarrow$ 2. Order Check



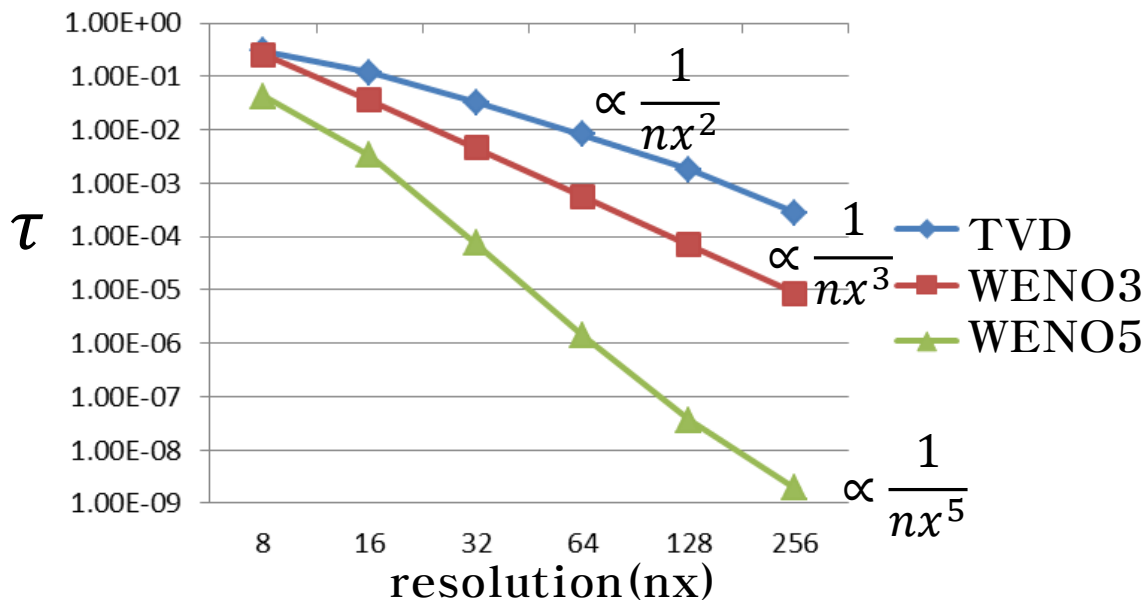
## Test Code

- 2<sup>nd</sup> order TVD
- 3<sup>rd</sup> order WENO3
- 5<sup>th</sup> order WENO5
- resolution = 32 tend = 100

## Numerical dissipation

$$\frac{\delta v_z(tend)}{\delta v_z(t=0)} = e^{-tend \cdot \tau}$$

$$\tau = -\frac{1}{tend} \ln \left( \frac{\delta v_z(tend)}{\delta v_z(t=0)} \right) \quad \text{decay rate}$$



# 2. Cylindrical Coordinate

## MHD equations

Primitive forms

density 
$$\frac{D\rho}{Dt} + \nabla \cdot (\rho \mathbf{v}) = 0$$

velocity 
$$\rho \frac{D\mathbf{v}}{Dt} + \nabla p - \nabla \times (\nabla \times \mathbf{v}) = \nabla \times (\nabla \times \mathbf{B}) \times \mathbf{B}$$

magnetic induction 
$$\nabla \times (\nabla \times \mathbf{B}) = \nabla \times \mathbf{j}$$

Gauss law 
$$\nabla \cdot \mathbf{B} = 0$$

adiabatic index

pressure 
$$\frac{Dp}{Dt} + \nabla \cdot (p \mathbf{v}) = 0$$

# 2. Cylindrical Coordinate

## MHD equations

$$\frac{\partial \delta \rho}{\partial t} + \rho_0 \frac{\partial \delta v_r}{\partial r} + \frac{\rho_0}{r} \delta v_r = 0$$

$$\rho_0 \frac{\partial \delta v_r}{\partial t} + \frac{\partial \delta p}{\partial r} + B_{\theta 0}(r) \frac{\partial \delta B_{\theta}}{\partial r} + \frac{1}{r} \delta B_{\theta} = 0$$

$$\frac{\partial \delta v_{\theta}}{\partial t} = 0$$

$$\frac{\partial \delta v_z}{\partial t} = 0$$

$$\frac{\partial \delta B_{\theta}}{\partial t} + B_{\theta 0}(r) \frac{\partial \delta v_r}{\partial r} - \frac{B_{\theta}}{r} \delta v_r = 0$$

$$\frac{\partial \delta B_z}{\partial t} = 0$$

$$\frac{\partial \delta p}{\partial t} + \gamma p_0 \frac{\partial \delta v_r}{\partial r} + \frac{\gamma}{r} p_0 \delta v_r = 0$$

Background equilibrium

$$B_{\theta 0}(r) = B_0 \left( \frac{R_0}{r} \right)$$

1D (r-dependence only)

$$\vec{\nabla} f = \frac{\partial f}{\partial r} \hat{r} \quad \vec{\nabla} \cdot \vec{F} = \frac{1}{r} \frac{\partial (r F_r)}{\partial r} \hat{r}$$

$$\vec{\nabla} \times \vec{F} = -\frac{\partial F_z}{\partial r} \hat{\theta} + \frac{1}{r} \frac{\partial (r F_{\theta})}{\partial r} \hat{z}$$

Fast wave assumption

$$\rho = \rho_0 + \delta \rho$$

$$v_r = \delta v_r$$

$$v_{\theta} = \delta v_{\theta}$$

$$v_z = \delta v_z$$

$$B_r = 0$$

$$B_{\theta} = B_{\theta 0}(r) + \delta B_{\theta}$$

$$B_z = \delta B_z$$

$$p = p_0 + \delta p$$

# Wave analysis

$$\frac{\partial}{\partial t} \left( \rho_0 \frac{\partial \delta v_r}{\partial t} + \frac{\partial \delta p}{\partial r} + B_{\theta 0}(r) \frac{\partial \delta B_{\theta}}{\partial r} + \frac{1}{r} \delta B_{\theta} \right) = 0$$

$$\rightarrow \rho_0 \frac{\partial^2 \delta v_r}{\partial t^2} + \frac{\partial}{\partial r} \left( \frac{\partial \delta p}{\partial t} \right) + B_{\theta 0}(r) \frac{\partial}{\partial r} \left( \frac{\partial \delta B_{\theta}}{\partial t} \right) + \frac{1}{r} \frac{\partial \delta B_{\theta}}{\partial t} = 0$$

$$\frac{\partial \delta p}{\partial t} + \gamma p_0 \frac{\partial \delta v_r}{\partial r} + \frac{\gamma}{r} p_0 \delta v_r = 0 \quad \frac{\partial \delta B_{\theta}}{\partial t} + B_{\theta 0}(r) \frac{\partial \delta v_r}{\partial r} - \frac{B_{\theta}}{r} \delta v_r = 0$$

$$\delta \vec{u}(t) \propto e^{i\omega t}$$

$$c_s = \sqrt{\gamma \frac{p_0}{\rho_0}} \quad c_A = \sqrt{\frac{B_0^2}{\rho_0}} \quad R = \frac{r}{R_0} \quad W = \omega R_0$$

$$\left( \frac{1}{R^2} + \frac{c_s^2}{c_A^2} \right) \frac{\partial^2 \delta v_r}{\partial r^2} - \frac{1}{R} \left( \frac{1}{R^2} - \frac{c_s^2}{c_A^2} \right) \frac{\partial \delta v_r}{\partial r} + \frac{1}{R^2} \left( \frac{1}{R^2} - \frac{c_s^2}{c_A^2} + \frac{W^2 R^2}{c_A^2} \right) \delta v_r = 0$$

When  $\frac{c_s^2}{c_A^2} = 0.01$ , numerically find  $\frac{W^2 R_0^2}{c_A^2} \rightarrow = 44.744$

At  $R = 1 (= R_0)$ ,  $\delta v_r = 0$ ,  $\frac{\partial \delta v_r}{\partial r} = 1$

$R_0 = 1$ ,  $c_A = 10 \rightarrow \omega = 66.89$

At  $R = 1.7$ ,  $\delta v_r = 0$ ,  $\frac{\partial \delta v_r}{\partial r} = 1$

Period =  $\frac{2\pi}{\omega} = 0.094$

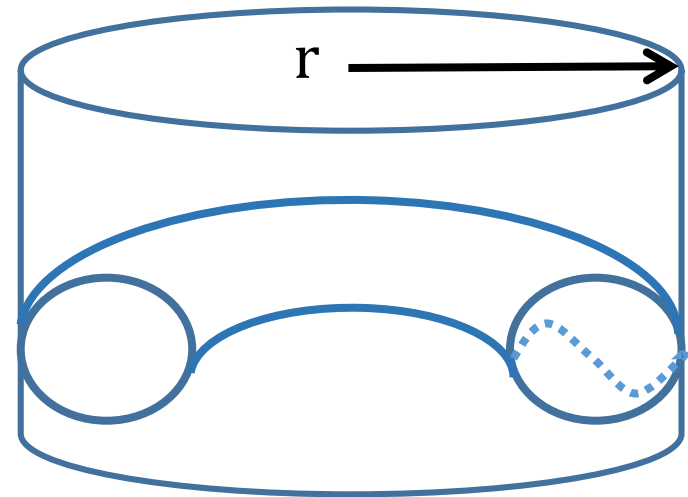
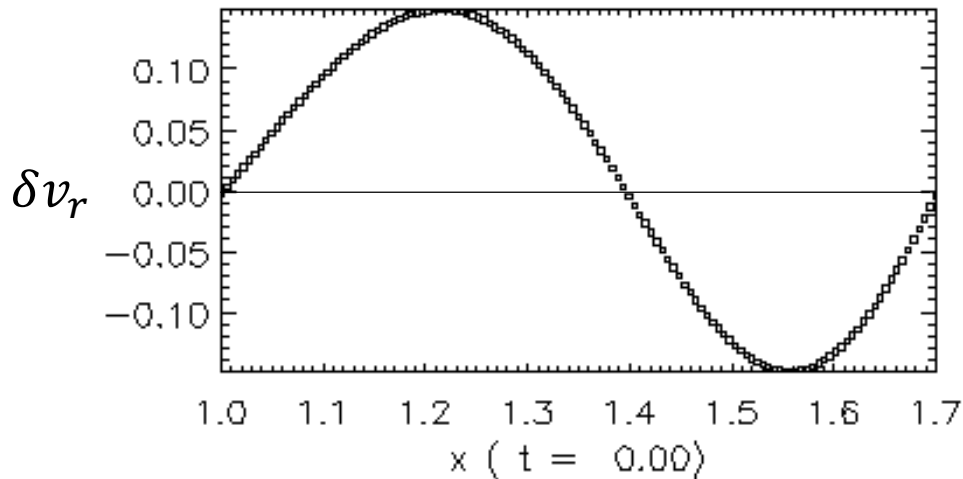


# Fast wave test

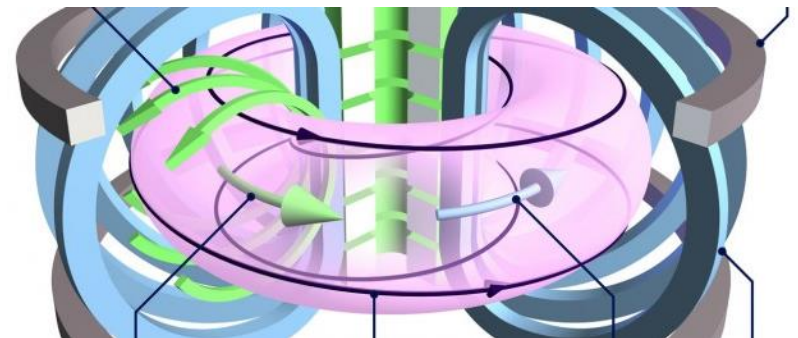
$$R_0 = 1, c_s = 1, c_A = 10, W = 6.689$$

$$\left( \frac{1}{R^2} + \frac{c_s^2}{c_A^2} \right) \frac{\partial^2 \delta v_r}{\partial r^2} - \frac{1}{R} \left( \frac{1}{R^2} - \frac{c_s^2}{c_A^2} \right) \frac{\partial \delta v_r}{\partial r} + \frac{1}{R^2} \left( \frac{1}{R^2} - \frac{c_s^2}{c_A^2} + \frac{W^2 R^2}{c_A^2} \right) \delta v_r = 0$$

initial condition for  $\delta v_r$



- Standing Wave
- Reflecting boundary
- Can be applied to TOKAMAK

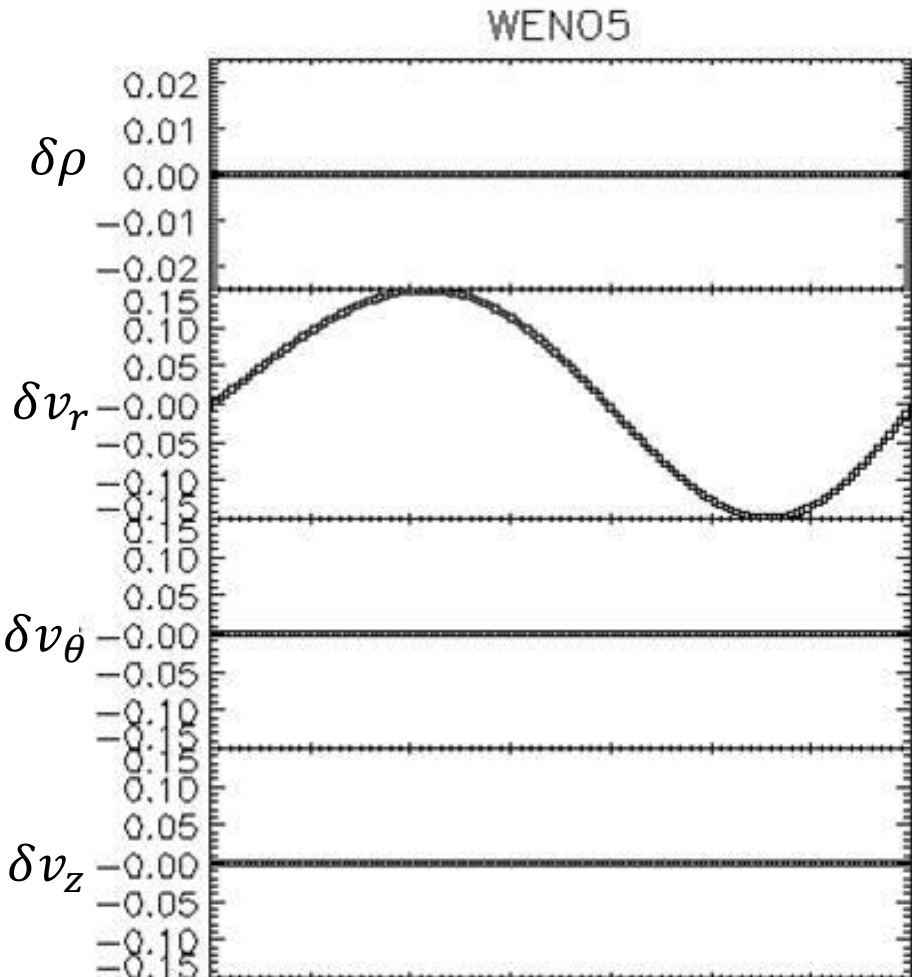


# Fast wave test

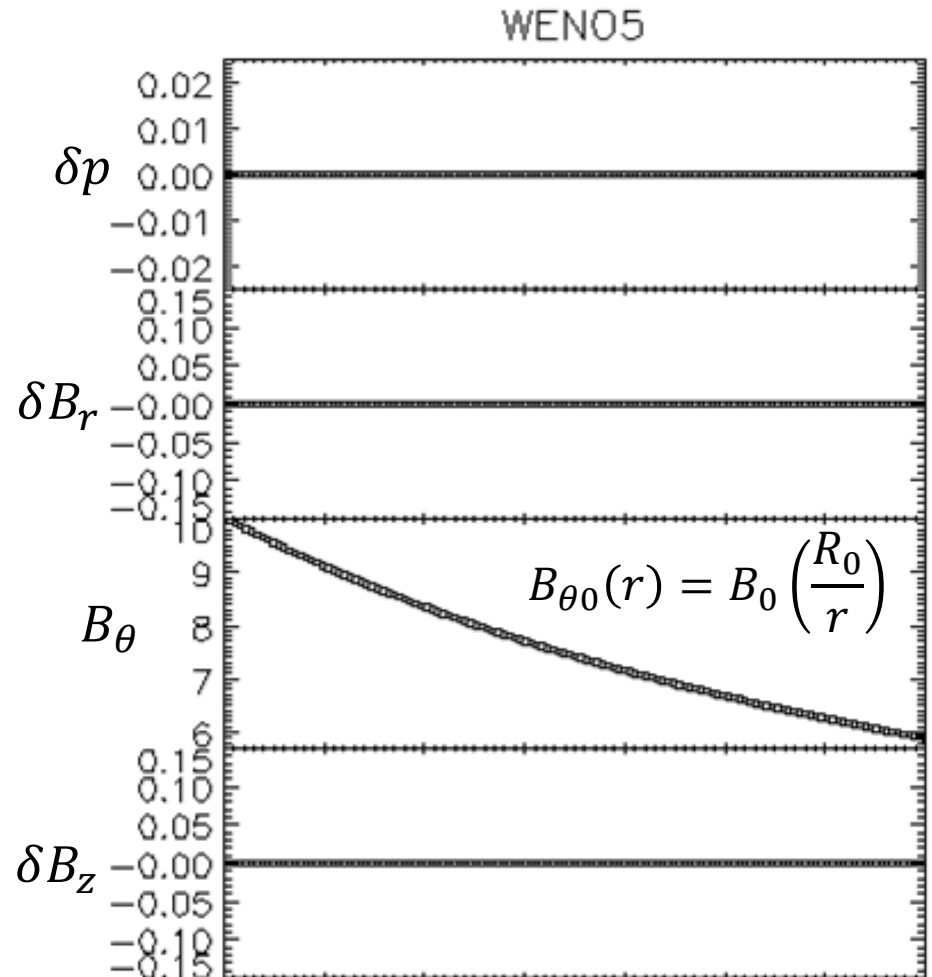
$$\rho_0 = 1, B_0 = 10, p_0 = 1/\gamma$$

$$v_{r0} = v_{\theta 0} = v_{z0} = B_{r0} = B_{z0} = 0$$

$$c_s^2 = \gamma \frac{p_0}{\rho_0} = 1 \quad c_A^2 = \frac{B_0^2}{\rho_0} = 100$$



x ( t = 0.000)

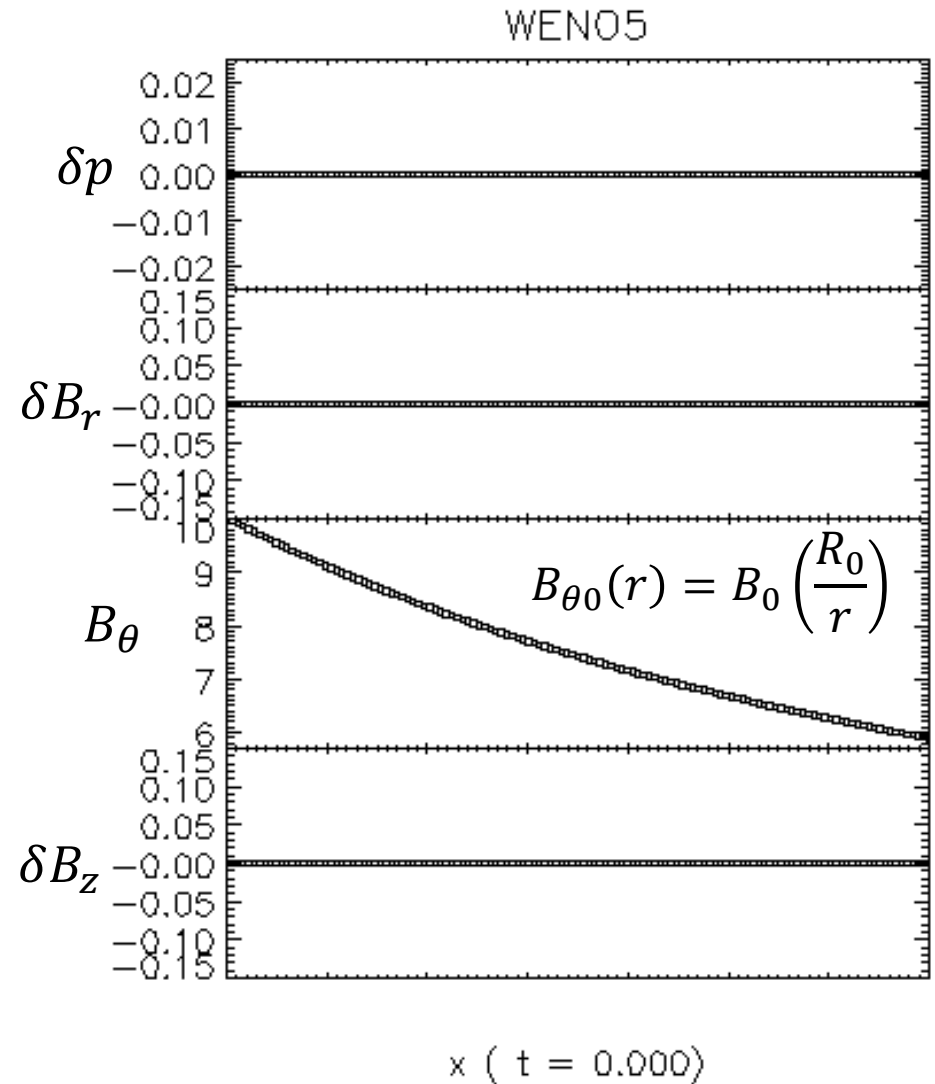
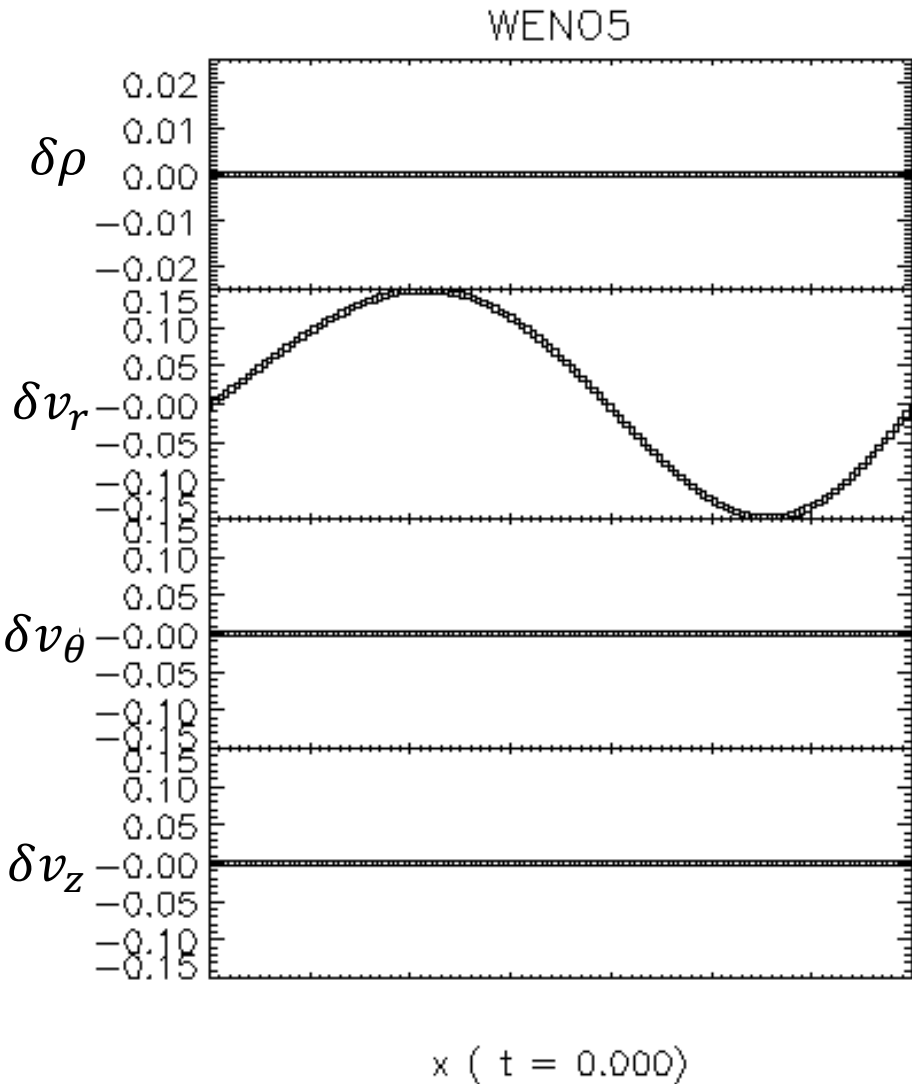


x ( t = 0.000)

# Fast wave test

$$\rho_0 = 1, B_0 = 10, p_0 = 1/\gamma$$
$$v_{r0} = v_{\theta 0} = v_{z0} = B_{r0} = B_{z0} = 0$$

$$c_s^2 = \gamma \frac{p_0}{\rho_0} = 1 \quad c_A^2 = \frac{B_0^2}{\rho_0} = 100$$



# Fast wave test

$$\rho_0 = 1, B_0 = 10, p_0 = 1/\gamma$$
$$v_{r0} = v_{\theta 0} = v_{z0} = B_{r0} = B_{z0} = 0$$

$$c_s^2 = \gamma \frac{p_0}{\rho_0} = 1 \quad c_A^2 = \frac{B_0^2}{\rho_0} = 100$$

